Product datasheet

Specification





variable speed drive, ATV320, 0.37 kW, 380...500 V, 3 phases, book

ATV320U04N4B

Main

Range of product	Altivar Machine ATV320
product or component type	Variable speed drive
Product specific application	Complex machines
variant	Standard version
Format of the drive	Book
mounting mode	Cabinet mount
Communication port protocol	Modbus serial CANopen
Option card	Communication module, CANopen Communication module, EtherCAT Communication module, Profibus DP V1 Communication module, PROFINET Communication module, Ethernet Powerlink Communication module, EtherNet/IP Communication module, DeviceNet
[Us] rated supply voltage	380500 V - 1510 %
Nominal output current	1.5 A
Motor power kW	0.37 kW for heavy duty
EMC filter	Class C2 EMC filter integrated
IP degree of protection	IP20

Complementary

Discrete input number	7
Discrete input type	STO safe torque off, 24 V DC, impedance: 1.5 kOhm DI1DI6 logic inputs, 24 V DC (30 V) DI5 programmable as pulse input: 030 kHz, 24 V DC (30 V)
Discrete input logic	Positive logic (source) Negative logic (sink)
Discrete output number	3
Discrete output type	Open collector DQ+ 01 kHz 30 V DC 100 mA Open collector DQ- 01 kHz 30 V DC 100 mA
Analogue input number	3
Analogue input type	Al1 voltage: 010 V DC, impedance: 30 kOhm, resolution 10 bits Al2 bipolar differential voltage: +/- 10 V DC, impedance: 30 kOhm, resolution 10 bits Al3 current: 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration), impedance: 250 Ohm, resolution 10 bits
Analogue output number	1

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Analogue output type	Software-configurable current AQ1: 020 mA impedance 800 Ohm, resolution 10 bits Software-configurable voltage AQ1: 010 V DC impedance 470 Ohm, resolution 10
	bits
Relay output type	Configurable relay logic R1A 1 NO electrical durability 100000 cycles Configurable relay logic R1B 1 NC electrical durability 100000 cycles
	Configurable relay logic R1C
	Configurable relay logic R2A 1 NO electrical durability 100000 cycles Configurable relay logic R2C
Maximum switching current	Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 250 V AC
	Relay output R1A, R1B, R1C on resistive load, cos phi = 1: 3 A at 30 V DC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7
	ms: 2 A at 250 V AC Relay output R1A, R1B, R1C, R2A, R2C on inductive load, cos phi = 0.4 and L/R = 7
	ms: 2 A at 30 V DC
	Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 250 V AC Relay output R2A, R2C on resistive load, cos phi = 1: 5 A at 30 V DC
Minimum switching current	Relay output R1A, R1B, R1C, R2A, R2C: 5 mA at 24 V DC
Method of access	Slave CANopen
4 quadrant operation possible	True
Asynchronous motor control	Voltage/frequency ratio, 5 points
orofile	Flux vector control without sensor, standard
	Voltage/frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor - Energy Saving
	Voltage/frequency ratio, 2 points
Synchronous motor control profile	Vector control without sensor
Fransient overtorque	170200 % of nominal motor torque
Maximum output frequency	0.599 kHz
Acceleration and deceleration ramps	Linear U
	S
	CUS
	Ramp switching Acceleration/deceleration ramp adaptation
	Acceleration/deceleration automatic stop with DC injection
Motor slip compensation	Automatic whatever the load
	Adjustable 0300 % Not available in voltage/frequency ratio (2 or 5 points)
Switching frequency	
Switching frequency	216 kHz adjustable 416 kHz with derating factor
Nominal switching frequency	4 kHz
Braking to standstill	By DC injection
Brake chopper integrated	True
Line current	2.1 A at 380 V (heavy duty)
Maximum input current	1.6 A at 500 V (heavy duty) 2.1 A
Maximum output voltage	500 V
Apparent power	1.4 kVA at 500 V (heavy duty)
Network frequency	5060 Hz
Relative symmetric network	
frequency tolerance	5 %
Prospective line Isc	5 kA
	4.4
Base load current at high overload	4 A
	Fan: 23.0 W at 380 V, switching frequency 4 kHz

With safety function Safe brake management (SBC/SBT)	False
With safety function Safe Operating Stop (SOS)	False
With safety function Safe Position (SP)	False
With safety function Safe programmable logic	False
With safety function Safe Speed Monitor (SSM)	False
With safety function Safe Stop 1 (SS1)	True
With sft fct Safe Stop 2 (SS2)	False
With safety function Safe torque	True
off (STO)	
off (STO) With safety function Safely Limited Position (SLP)	False
With safety function Safely	False
With safety function Safely Limited Position (SLP)	
With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI)	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive
With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type	False Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive
With safety function Safely Limited Position (SLP) With safety function Safe Direction (SDI) Protection type Width	Input phase breaks: drive Overcurrent between output phases and earth: drive Overheating protection: drive Short-circuit between motor phases: drive Thermal protection: drive 45.0 mm

Environment

Operating position	Vertical +/- 10 degree
Product certifications	CE ATEX NOM GOST EAC RCM KC
marking	CE ATEX UL CSA EAC RCM
Standards	IEC 61800-5-1
Electromagnetic compatibility	Electrostatic discharge immunity test level 3 conforming to IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 conforming to IEC 61000-4-3 Electrical fast transient/burst immunity test level 4 conforming to IEC 61000-4-4 1.2/50 µs - 8/20 µs surge immunity test level 3 conforming to IEC 61000-4-5 Conducted radio-frequency immunity test level 3 conforming to IEC 61000-4-6 Voltage dips and interruptions immunity test conforming to IEC 61000-4-11
Environmental class (during operation)	Class 3C3 according to IEC 60721-3-3 Class 3S2 according to IEC 60721-3-3
Maximum acceleration under shock impact (during operation)	150 m/s² at 11 ms
Maximum acceleration under vibrational stress (during operation)	10 m/s² at 13200 Hz
Maximum deflection under vibratory load (during operation)	1.5 mm at 213 Hz
Permitted relative humidity (during operation)	Class 3K5 according to EN 60721-3

Volume of cooling air	9.4 m3/h
Overvoltage category	III
Regulation loop	Adjustable PID regulator
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn
Pollution degree	2
Ambient air transport temperature	-2570 °C
Ambient air temperature for operation	-1050 °C without derating 5060 °C with derating factor
Ambient air temperature for storage	-2570 °C

Packing Units

Unit Type of Package 1	PCE
Number of Units in Package 1	1
Package 1 Height	8.500 cm
Package 1 Width	27.500 cm
Package 1 Length	32.500 cm
Package 1 Weight	2.273 kg
Unit Type of Package 2	S06
Number of Units in Package 2	24
Package 2 Height	75.000 cm
Package 2 Width	60.000 cm
Package 2 Length	80.000 cm
Package 2 Weight	68.848 kg



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Guide to assess a product's sustainability >





Transparency RoHS/REACh

Resource performance



Upgraded Components Available

Well-being performance



Mercury Free



Rohs Exemption Information

Yes

Certifications & Standards

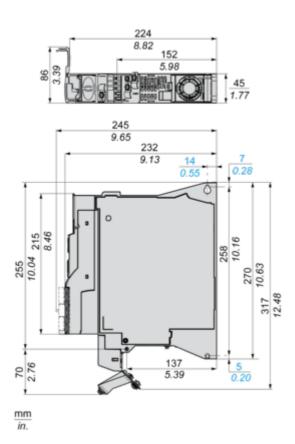
Reach Regulation	REACh Declaration
Eu Rohs Directive	Pro-active compliance (Product out of EU RoHS legal scope)
China Rohs Regulation	China RoHS declaration
Environmental Disclosure	Product Environmental Profile
Weee	The product must be disposed on European Union markets following specific waste collection and never end up in rubbish bins
Circularity Profile	End of Life Information

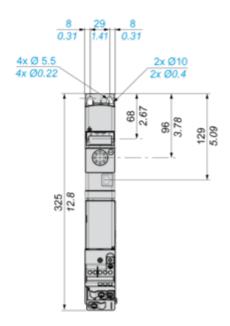
Dimensions Drawings

Dimensions

Bottom, Right and Front View

in.

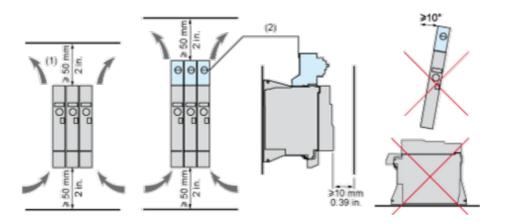




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Mounting and Clearance

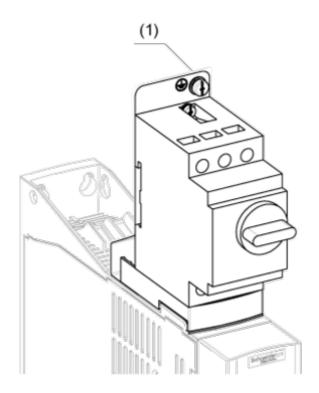
Mounting and Clearance



- (1) Minimum value corresponding to thermal constraints. (2) Optional GV2 circuit-breaker

Option: Protection Device, GV2 circuit-breaker

NOTE: The product overall height dimension, including GV2 adapter and EMC plate mounted, becomes 424 mm (16.7 in.) instead of 325 mm (12.80 in.)



(1) Ground screw (HS type 2 - 5x12)

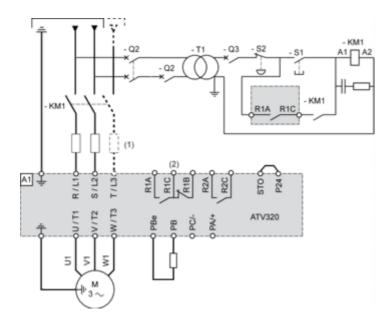
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Connections and Schema

Connection Diagrams

Diagram with Line Contactor

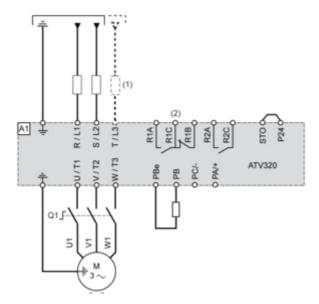
Connection diagrams conforming to standards ISO13849 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

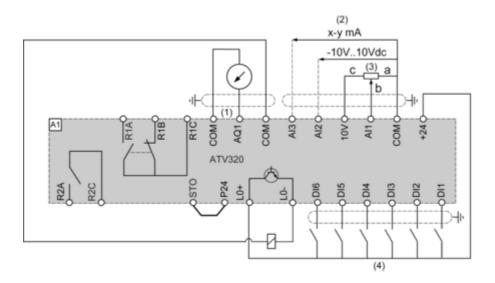
Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- (1) Line choke (if used)
- (2) Fault relay contacts, for remote signaling of drive status

Control Connection Diagram in Source Mode



- (1) Analog output
- (2) Analog inputs
- (3) Reference potentiometer (10 kOhm maxi)
- (4) Digital inputs

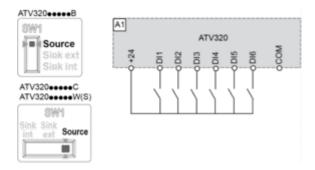
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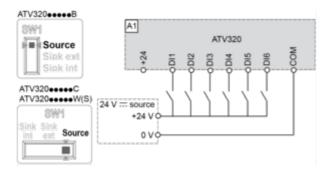
Digital Inputs Wiring

The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs.

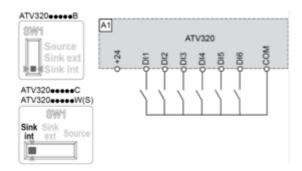
Switch SW1 set to "Source" position and use of the output power supply for the DIs.



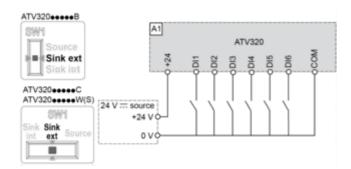
Switch SW1 set to "Source" position and use of an external power supply for the DIs.



Switch SW1 set to "Sink Int" position and use of the output power supply for the DIs.



Switch SW1 set to "Sink Ext" position and use of an external power supply for the Dls.

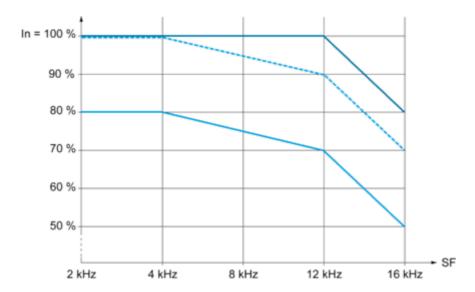


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Performance Curves

Derating Curves

Derating curve for the nominal drive current (In) as a function of temperature and switching frequency (SF).



40 °C (104 °F) - Mounting type A, B and C 50 °C (122 °F) - Mounting type A, B and C 60 °C (140 °F) - Mounting type B and C

In: Nominal Drive Current SF: Switching Frequency